EAST Search History

Ref#	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	526	(702/173).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/05 11:49
S2	1412	(702/142,143,144,145,146,147,148,154,175,176).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/09 17:08
S3	45	((inclinometer\$1 inclinat\$3) with ((measur\$4 determin\$3 obtain\$3) and calibrat\$3)) and ((vehicl\$3 car\$1 automobil\$3 motor\$1bike\$1) with (mass \$3 weight\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 11:57
S4	1	("6249735").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/05 11:57
S5	10	("4548079" "5925087").PN. OR ("6249735").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:32
S6	2	((least\$1 with squar\$3) (best\$1fit\$3 (best\$3 with fit\$3))) and S3	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:39
S7	0	(rotat\$3 near rate\$1) and (reinitializ\$3) and (clutch\$3 with actuat\$3) and (togrue with engine\$1) and (brake\$1 with actuat\$3) and (motive\$1 with force\$1 with result\$3) and (aerodynamic\$3 with force\$3) and (roll\$3 with force\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:41
S8	935	(rotat\$3 with rat\$3) and (vehicl\$3 with speed\$3) and (corner\$3 with vehicle \$1)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:43
S9	13683	(clutch\$3 with actuat\$3) and (brake\$1 with actuat\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:43
S10	21775	(motive\$1 with force\$1)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:43
S11	8295	(aerodynamic\$3 with force\$1)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:44

S12	191362	roll\$3 with force\$1	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:44
S13	1	(inertial with force\$1 with transmis\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 14:44
S14	1	((inertial with force\$1) with transmis\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:03
S15	20035	((inert\$3 with forc\$3) and transmi\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:00
S16	1	S9 and S10 and S11 and S12 and S15	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:02
S17	1	S9 and S10 and S11 and S12	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:03
S18	1	S9 and S10 and S11	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:03
S19	133	S10 and S11	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:03
S20	14	S10 and S11 and S15	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:03
S21	1022	(vehicl\$3 car\$1 automobile\$1) with (mass weight\$1) with estimat\$3	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:56
S22	5	((vehicl\$3 car\$1 automobile\$1) with (mass weight\$1) with estimat\$3) and ((inclinat\$3 inclin\$5) with variat\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:48
S23	0	S22 and S6	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:39

S24	45		US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:39
S25	0	S22 and S3	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:39
S26	520	(vehicl\$3 with (mass\$3 weight\$3)) and (model\$1 with error\$1)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:49
S27	3675	(vehicl\$3 with (mass\$3 weight\$3)) and ((predetermin\$3 referenc\$3 profil\$3) with (mass))	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:50
S28	0	S26 and 27]	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:50
S29	49	S26 and S27	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:50
S30	9528	(least\$1squar\$3 best\$1fit\$3) with (algorithm equation\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:55
S31	2	((least\$1squar\$3 best\$1fit\$3) with (algorithm equation\$3)) and ((predetermin\$3 referenc\$3) with (mass\$3 weight\$1)) and (converg\$3 with criter\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:54
S32	3	S29 and S30	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:55
S33	128	((vehicl\$3 car\$1 automobile\$1) with (mass weight\$1) with estimat\$3) and (best\$1fit\$3 least\$1squar\$3 regress\$3 recursiv\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:56
S34	5	S33 and S1	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 15:56
S35	6	("6249735" "6293632" "6298300" "6339739" "6339749" "6450588"). PN. OR ("6839615").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/05 16:07

S36	1		US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/05 16:07
S37	1129	(vehicle\$1 (motor\$1 with vehicle\$1) car\$1) with ((mass\$3 weigh\$3) with estimat\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:04
S38	212	(recursiv\$3 with least with squar\$3) and (kalman with filter\$3) and (converg \$4)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:31
S39	9	S37 and S38	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:15
S40	14	recursiv\$3 with mass with vehicl\$3	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:29
S41	3	S40 and (kalman with filter\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:30
S42	0	S40 and (kalman with filter\$3) and converg\$3	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:30
S43	16	(recursiv\$3 with least with squar\$3) and (kalman with filter\$3) and (converg \$4) and (vehicl\$3 with (weigh\$3 mass\$3 load\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:01
S44	0	(recursiv\$3 with least with squar\$3) and (kalman with filter\$3) and (converg \$4) and (vehicl\$3 with (weigh\$3 mass\$3 load\$3)) and (valid\$3 with (model \$1 threshold\$1 referenc\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:37
S45	0	(((mass weigh\$3) with (car\$1 automobil\$1 vehicl\$3)) with (determin\$3 obtain\$3 estimat\$3 calculat\$3)) and (inclin\$3 with acclerat\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:37
S46	1149	((motor\$1 with vehicl\$3) automobile\$1 car\$1 vehicl\$3) with (estimat\$3 with (weigh\$3 mass\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:44
S47	226	(701/124).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/09 16:45

S48	12	- 4	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:45
S49	1		US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 16:45
S50	1	,	US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/09 16:45
S51	0	\$4) and (vehicl\$3 with (weigh\$3 mass\$3 load\$3)) and (mass\$3 with	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:02
S52	1		US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:03
S53	75	estimat\$3)) and (accelerat\$3 with (longitud\$3 lateral\$1)) and ((inclin\$3 angl	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:04
S54	0		US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:04
S55	0	estimat\$3) and (mass with referenc\$3) and ((surfac\$3 and load\$3 and	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:06
S56	1	\$3)with (car\$1 automobil\$3 vehicl\$3)) and (inert\$3 with force\$1) and	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:08
S57	1	weigh\$3)with (car\$1 automobil\$3 vehicl\$3)) and (inert\$3 with force\$1) and	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:08
S58	0	S57 and S47	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:08
S59	1913	(702/142,143,144,145,146,147,148,154,175,176,173).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/09 17:08

S60	0	S57 and S59	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:08
S61	0	S59 and S53	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:09
S62	2	S53 and S47	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/09 17:09
S63	5329	(((vehicl\$3 car\$1 air\$1craft\$1 automobile\$1 motor\$1vehicle\$1) near (load \$3 weigh\$3 mass\$3)) with (measur\$3 estimat\$3 obtain\$3 calculat\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/10 11:30
S64	45	S63 and ((kalman with filter\$3) (recursive\$1 with least with squar\$3)) and (converg\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2007/10/10 11:56
S65	1	("20070038357").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/10/10 15:16
S66	6	("1425559").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/10/10 15:16
S67	0	2007/0038357	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:30
S68	1	"20070038357"	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:30
S69	1981	(702/142,143,144,145,146,147,148,154,173,175,176).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/05/01 15:42
S70	233	(701/124).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/05/01 15:42
S71	13917	(clutch\$3 with actuat\$3) and (brake\$1 with actuat\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:42

\$72	15	clutch\$1pedal\$1 with position\$3 with (sens\$3 actuat\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:43
S73	20823	((inert\$3 with forc\$3) and transmi\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:43
574	6	((vehicl\$3 car\$1 automobile\$1) with (mass weight\$1) with estimat\$3) and ((inclinat\$3 inclin\$5) with variat\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:43
S75	0	S72 and (S69 S70)	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:44
S76	7	S71 and S72	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:44
 377	6	(S71 and S72) not S68	US-PGPUB; USPAT; USOCR	OR	ON	2008/05/01 15:44
S78	967	(702/142-148).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2009/01/12 12:42
S79	1176	(702/173-176).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2009/01/12 12:42
S80	242	(701/124).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2009/01/12 12:42
S81	681	(701/37).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2009/01/12 12:42
S82	315	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:44
583	16	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (S78 S79 S80 S81)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:44

S84	0	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (S78 S79 S80 S81) and (least\$1squar\$3 with (longitud\$3 with accelerat\$4))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:45
S85	0	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (S78 S79 S80 S81) and (longitud\$3 with accelerat \$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:46
S86	1	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (S78 S79 S80 S81) and (accelerat\$4) and (motion \$3) and (inclinat\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:46
S87	0	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (S78 S79 S80 S81) and (accelerat\$4) and (motion \$3) and (inclinat\$4) and (slope\$1 with sens\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:47
S88	0	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (S78 S79 S80 S81) and (accelerat\$4) and (motion \$3) and ((slope\$1 inclin\$4) with sens\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:47
S89	6	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (accelerat\$4) and (motion\$3) and ((slope\$1 inclin\$4) with sens\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:48
S90	1	(estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (accelerat\$4) and (motion\$3) and ((slope\$1 inclin\$4) with sens\$3) and (recursiv\$3 with algorithm\$1)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:49
S91	0	((estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (accelerat\$4) and (motion\$3) and ((slope\$1 inclin\$4) with sens\$3) and (recursiv\$3 with algorithm\$1)) and (S78 S79 S80 S81)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:50
S92	1	(((estimat\$3 calculat\$3 obtain\$3) with (total with mass with (object\$1 vehicl \$3 automobil\$3)) and (accelerat\$4) and (motion\$3) and ((slope\$1 inclin\$4) with sens\$3) and (recursiv\$3 with algorithm\$1))).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:50

S93	0	S92 and (S78 S79 S80 S81)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 12:50
S94	2	((least\$1squar\$3 best\$1fit\$3) with (algorithm equation\$3)) and ((predetermin\$3 referenc\$3) with (mass\$3 weight\$1)) and (converg\$3 with criter\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2009/01/12 12:51
S95	6	((vehicl\$3 car\$1 automobile\$1) with (mass weight\$1) with estimat\$3) and ((inclinat\$3 inclin\$5) with variat\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2009/01/12 12:51
S96	1	S94 and S95	US-PGPUB; USPAT; USOCR	OR	ON	2009/01/12 12:51
S97	85	(702/154).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO	OR	OFF	2009/01/12 14:10
S98	0	S92 and S97	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO	OR	ON	2009/01/12 14:10

1/12/2009 2:48:44 PM

 $\textbf{C:} \textbf{Documents and Settings} \\ \textbf{phuynh1} \\ \textbf{My Documents} \\ \textbf{EAST} \\ \textbf{Workspaces} \\ \textbf{10563158.wsp}$